

POLYNOMIALLY SOLVABLE SPECIAL CASES OF THE PATH-TSP

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joint work with

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- 1 Introduction
 - Statement of the problem
 - Complexity and the relationship to TSP
 - Polynomially solvable special cases
- 2 The Path-TSP with a Demidenko distance matrix
 - Demidenko matrices, pyramidal paths and tours
 - Forbidden pairs of arcs
 - $(1, t)$ -Path-TSP: the structure of optimal paths
 - (s, t) -Path-TSP, $s \neq 1$: the structure of optimal paths
- 3 The Path-TSP with a Van der Veen distance matrix
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 - The shortest path model
 - The general case
- 4 Conclusions and outlook

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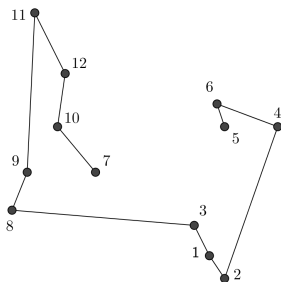
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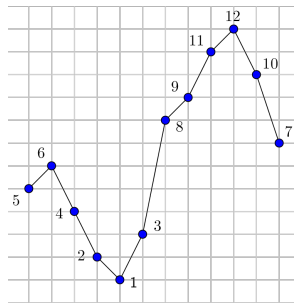
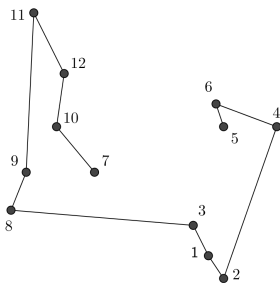
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Recently: the approximability of Path-TSP is the same as for TSP, up to an arbitrarily small error. (Traub et al. 2019)

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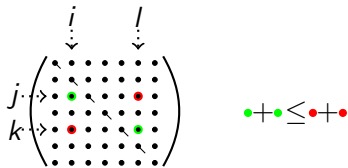
Demidenko matrices and pyramidal paths

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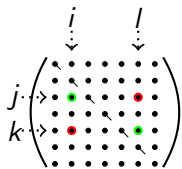
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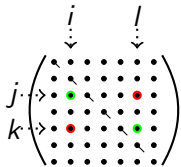


$$\text{green} + \text{green} \leq \text{red} + \text{red}$$

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Demidenko matrices and pyramidal paths

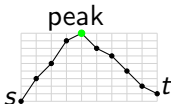
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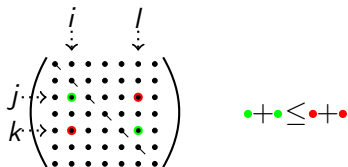
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λ -pyramidal path



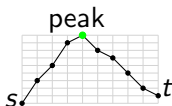
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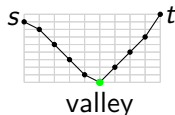


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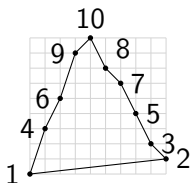
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A closed λ -pyramidal or ν -pyramidal path is called a **pyramidal tour**.

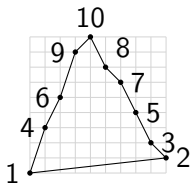
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Theorem (Demidenko, 1979)

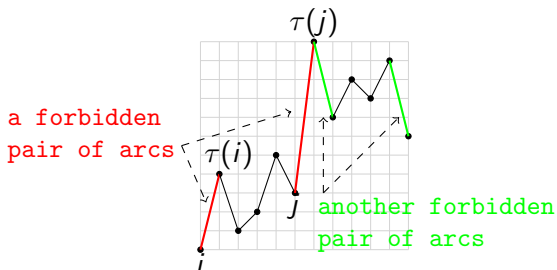
For a set of cities with a Demidenko distance matrix there exists an optimal tour which is pyramidal. In this case the TSP on n cities can be solved in $O(n^2)$ time by dynamical programming.

Forbidden pairs of arcs

In an (s, t) -path τ a pair of arcs $(i, \tau(i))$ and $(j, \tau(j))$ is called a **forbidden pair of arcs** if either $i < j < \tau(i) < \tau(j)$ or $i > j > \tau(i) > \tau(j)$ holds.

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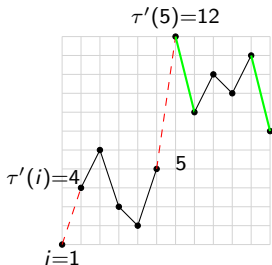
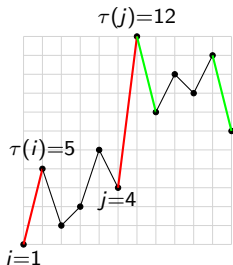
The forbidden pairs lemma: In the case of a Demidenko distance matrix there always exist an optimal (s, t) -TSP-path without forbidden pairs of arcs, for any s and t .

Proof of the forbidden pairs lemma

Exchange argument: replace the forbidden pair of arcs $(i, \tau(i)), (j, \tau(j))$ in an optimal path by the non-forbidden pair $(i, j), (\tau(i), \tau(j))$ and reverse the $(\tau(i), j)$ -subpath. The resulting path is again optimal.

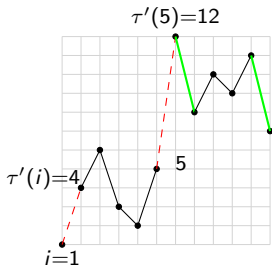
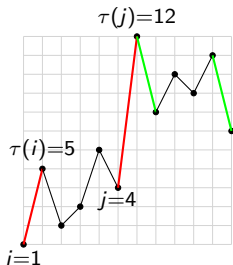
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After repeating the exchange argument a finite number of times we get an optimal (s, t) -TSP-path without forbidden pairs of arcs.

The special structure of optimal paths

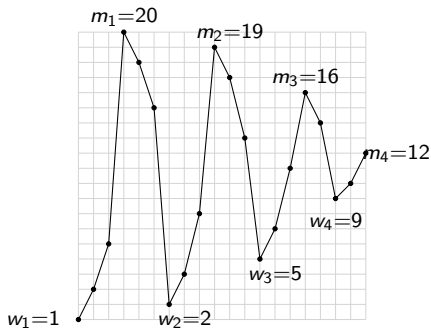
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Lemma 2: For any t there exist an optimal $(1, t)$ -TSP-path without forbidden pairs of arcs in which the peaks decrease and the valleys increase along the path.



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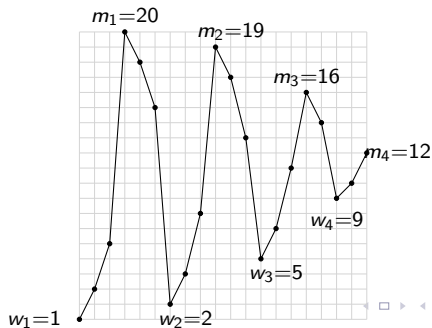
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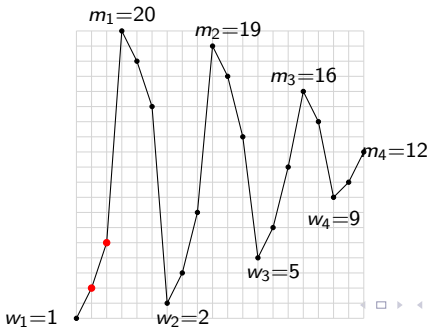
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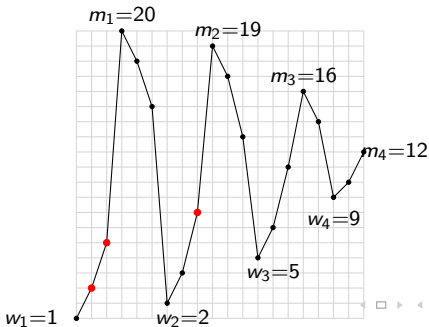
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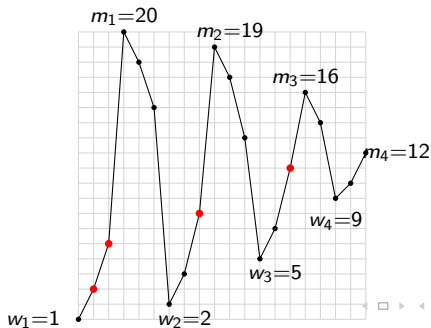
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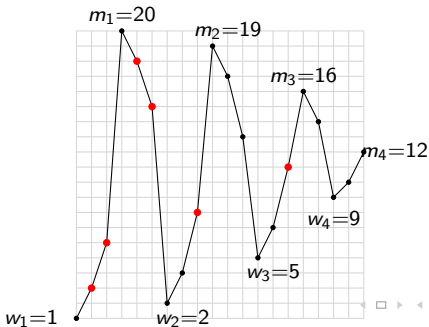
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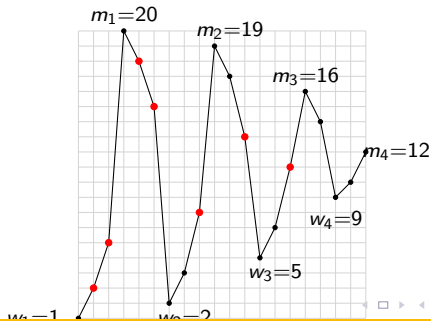
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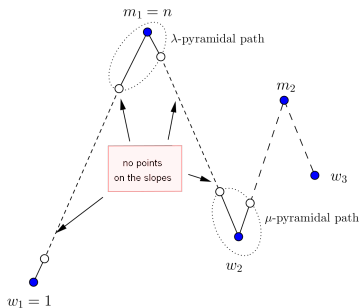
Lemma 3: In an optimal $(1, t)$ -TSP-path without forbidden pairs of arcs and with decreasing peaks and increasing valleys, the following holds for any alternating sequence of valleys and peaks w_1, m_1, w_2, m_2, w_3 :

- (I) The (w_1, m_1) -subpath contains no indices i such that $w_2 < i < m_2$.
- (II) The (m_1, w_2) -subpath contains no indices j such that $w_3 < j < m_2$.

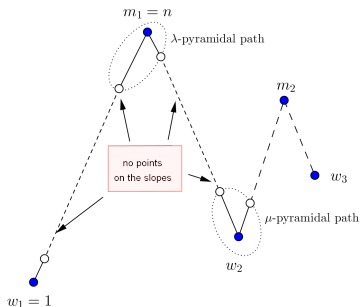


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Theorem: For every destination city t the $(1, t)$ -Path-TSP on n cities with a Demidenko distance matrix can be solved in $O(n^5)$ time by dynamic programming.

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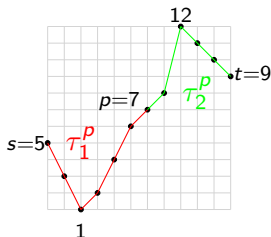
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- (C) There exists a city p such that $\tau = \langle \tau_1^p, \tau_2^p \rangle$, where τ_1^p visits all cities in $\overline{1, p-1}$ and τ_2^p visits all cities in $\overline{p, n}$.

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The (s, t) -Path-TSP with a Demidenko distance matrix

Theorem: The (s, t) -Path-TSP on n cities with a Demidenko distance matrix can be solved in $O((t - s)n^5)$ time for any origin city s and any destination city t , $1 < s < t < n$.

1 Introduction

- Statement of the problem
- Complexity and the relationship to TSP
- Polynomially solvable special cases

2 The Path-TSP with a Demidenko distance matrix

- Demidenko matrices, pyramidal paths and tours
- Forbidden pairs of arcs
- $(1, t)$ -Path-TSP: the structure of optimal paths
- (s, t) -Path-TSP, $s \neq 1$: the structure of optimal paths

3 The Path-TSP with a Van der Veen distance matrix

- Van der Veen matrices and pyramidal tours
- Forbidden pairs of arcs
- The structure of optimal paths
- The dynamic programming approach

4 Conclusions and outlook

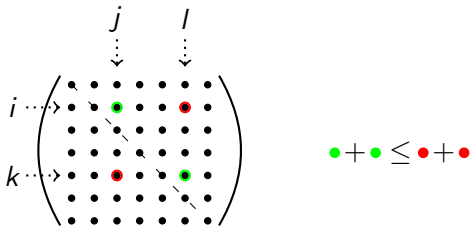
Van der Veen matrices and pyramidal tours

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Definition: A symmetric matrix $C = (c_{ij})$ is called a **Van der Veen matrix** if $c_{ij} + c_{kl} \leq c_{il} + c_{kj}$, for all $1 \leq i < j < k < l \leq n$.

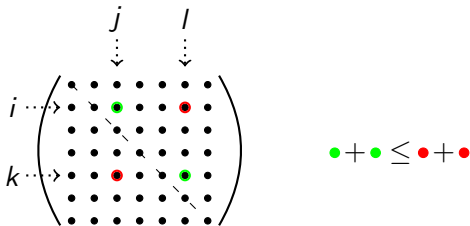
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Theorem (Van der Veen, 1994)

For a set of cities with a Van der Veen distance matrix, there exists an optimal tour which is pyramidal. In this case the TSP on n cities can be solved in $O(n^2)$ time by dynamical programming.

Forbidden pairs of arcs

In an (s, t) -path τ a pair of arcs $(i, \tau(i))$ and $(j, \tau(j))$ is called a **forbidden pair of arcs** of type A or B if the condition (A) or (B) holds

(A) $i < j < \tau(j) < \tau(i)$ or $i > j > \tau(j) > \tau(i)$

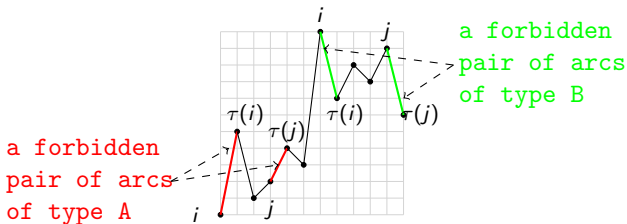
(B) $i < j < j + 1 < \tau(i) < \tau(j)$ or $\tau(j) < \tau(i) < \tau(i) + 1 < j < i$

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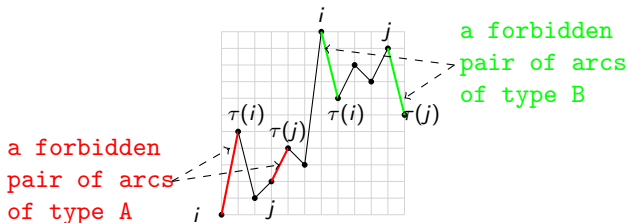


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The forbidden pairs lemma: In the case of a Van der Veen distance matrix (c_{ij}) , there is an optimal (s, t) -TSP-path without forbidden pairs of arcs for any s and t .

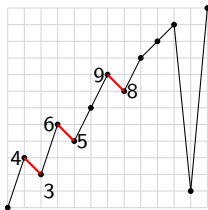
Particular subpaths

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An arc $(k + 1, k)$ in a path $\tau = \langle \dots, i, k + 1, k, j, \dots \rangle$ with $i = \tau^{-1}(k + 1) < \tau(k + 1) = k < k + 1 < \tau(k) = j$ is called a **short zigzag** with peak $k + 1$ (and valley k).

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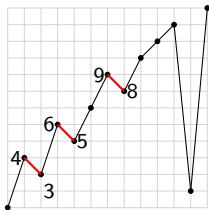
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Short zigzag lemma: Let τ be a $(1, n)$ -TSP-path without forbidden pairs of arcs such that $\tau(k + 1) = k$ for some $k \in \overline{1, n - 1}$. Then $(k + 1, k)$ is a short zigzag with peak $k + 1$ and $\tau(k) \in \{k + 2, k + 3\}$, $\tau^{-1}(k + 1) \in \{k - 2, k - 1\}$ hold.

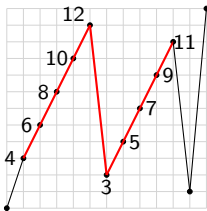
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A path $\tau_{p,v} = \langle v + 1, v + 3, \dots, p - 2, p, v, v + 2, \dots, p - 1 \rangle$ with $v < p - 1$, and v, p of different parity, $v, p \in \overline{1, n}$, is called a **long zigzag** with peak p and valley v and is denoted by $\tau_{p,v}$.

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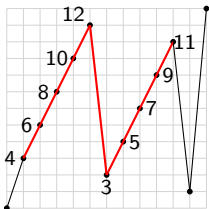
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Long zigzag lemma: Let τ be a $(1, n)$ -TSP-path without forbidden pairs of arcs. Let p be a peak and let $v < p - 1$ be the first valley reached after p in τ . Then the long zigzag $\tau_{p,v}$ is a subpath of τ . Moreover $\tau_{p,v}$ is preceded by $x \in \{v - 1, v - 2\}$ and is succeeded by $y \in \{p + 1, p + 2\}$.

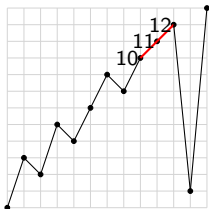
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For two cities i, j with $i, j \in \overline{0, n+1}$, $i < j - 1$ the monotone increasing subpath $\langle i + 1, \dots, j - 1 \rangle$ is called a **chain between i and j** and is denoted by $ch(i, j)$.

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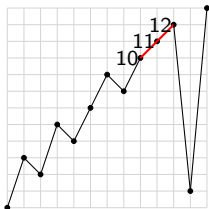
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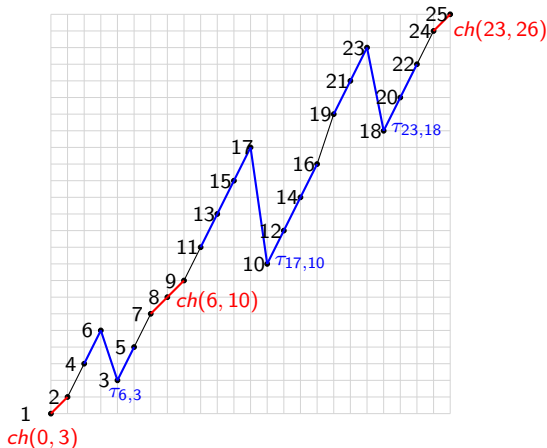
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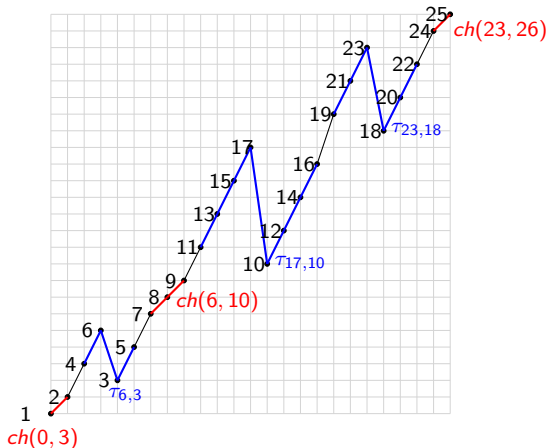
Zigzag path lemma: Any $(1, n)$ -TSP-path without forbidden pairs of arcs is a zigzag path.

Example of a zigzag path

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Modelling zigzag paths on a directed graph with $O(n)$ vertices

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The vertex set: $V_n := \{1, 2, \dots, n\} \cup \{\bar{3}, \bar{4}, \dots, \overline{n-1}\} \cup \{\underline{2}, \underline{3}, \dots, \underline{n-2}\}$.

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 - from a zigzag with peak $k+1$ to a zigzag with valley $k+2$: $(\underline{k}, \overline{k+3})$
 - from a zigzag with peak $k+1$ to a chain: $(\underline{k}, \underline{k+2})$
 - from a chain to a zigzag with valley $k+1$: $(\underline{k}, \overline{k+2})$

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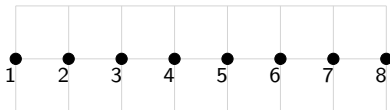
An example for $n = 8$

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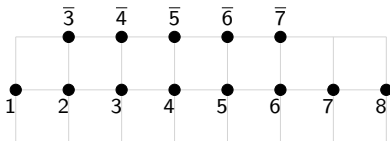
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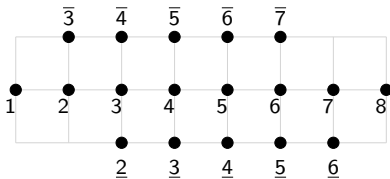
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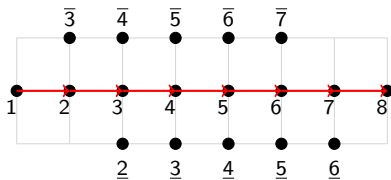
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arcs contained in chains

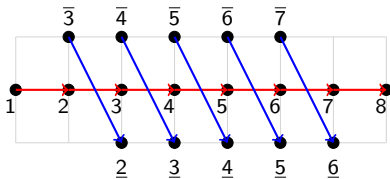
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Theorem: The shortest $(1, n)$ -TSP-path on n cities with a Van der Veen distance matrix can be found in $O(n^2)$ time. Moreover, for each $k \in \overline{1, n}$ a family of shortest $(1, k)$ -TSP-path over the cities $\overline{1, k}$ can be found in $O(n^2)$ time.

An example for $n = 8$



arcs contained in chains

short zigzags

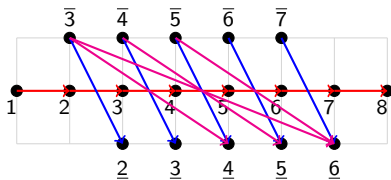
The $(1, n)$ -Path-TSP with a Van der Veen distance matrix

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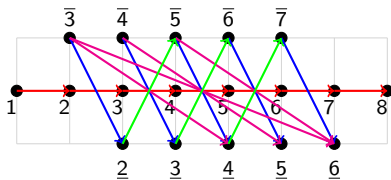
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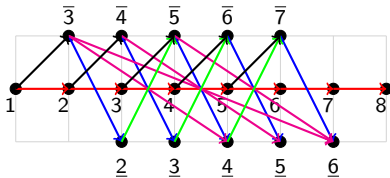
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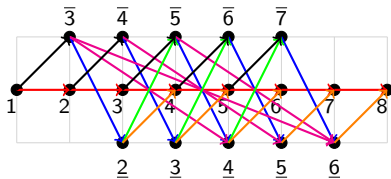
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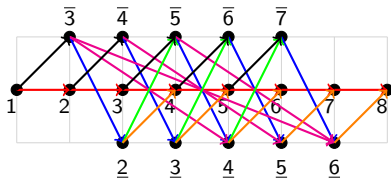
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The general case

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Theorem: For any $s, t \in \{1, 2, \dots, n\}$, $1 < s < t < n$, a shortest (s, t) -TSP-path on n cities with a Van der Veen distance matrix can be found in $O(n^3)$ time.

Conclusions

- We discussed two new polynomially solvable special cases of the Path-TSP:
 - (I) n cities with a Demidenko distance matrix: solvable in $(t - s)n^5$ for general s and t , solvable in $O(n^5)$ for $s = 1$, solvable in $O(n)$ for $s = 1$, $t = n$.
 - (II) n cities with a Van der Veen distance matrix: solvable in $O(n^3)$ for general s and t , solvable in $O(n^2)$ if $s = 1$.

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 - (II) n cities with a Van der Veen distance matrix: solvable in $O(n^3)$ for general s and t , solvable in $O(n^2)$ if $s = 1$.
- The optimal (s, t) -TSP-paths can be found among paths with a particular combinatorial structure avoiding forbidden pairs of arcs.
- The sets of (s, t) -TSP-paths with the above structure are of exponential size.
- The shortest (s, t) -TSP-path over each of the sets above can be determined in polynomial time.

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Thanks a lot for the attention!